

New discussion on approximate controllability results for fractional Sobolev type Volterra-Fredholm integro-differential systems of order $1 < r < 2$

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Abstract

In our article, we are primarily concentrating on approximate controllability results for fractional Sobolev type Volterra-Fredholm integro-differential inclusions of order $1 < r < 2$. By applying the results and ideas belongs to the cosine function of operators, fractional calculus and fixed point approach, the main results are established. Initially, we establish the approximate controllability of the considered fractional system, then continue to examine the system with the concept of nonlocal conditions. In the end, we present an example to demonstrate the theory.

KEYWORDS

approximate controllability, fractional derivative, integro-differential system, nonlocal conditions, Sobolev-type system

1 | INTRODUCTION

Fractional calculus, as a significant area of Mathematics, was initiated in 1695. It was nearly simultaneously as classical calculus. Recently, the ideas about fractional calculus became effectively applied to different regions, and the investigators progressively found that the fractional calculus can well portray several non-local events in the areas of natural science and architecture. Presently, the mainstream

areas of fractional calculus containing rheology, liquid stream, diffusive transport likened to dispersion, dynamical cycles in self-comparable and porous structures, viscoelasticity, and, optics, etc. The effective utilization of the fractional systems in these areas has incited several researchers to contemplate their mathematical estimate strategies, as the diagnostic arrangements are commonly hard to get. For interesting results related to fractional dynamical systems, the readers may refer to the books [1–4] and the articles [5–19].

Control theory is a significant region of utilization situated in Mathematics which manages the structure and examination of control frameworks. Recently, controllability concerns for different sorts of nonlinear dynamical frameworks in infinite dimensional spaces became examined in numerous research articles by utilizing various types of techniques. A broad list of these distributions can be discovered in [6, 9, 11–16, 18–24, 43, 44–50]. The studies about existence and controllability related to fractional evolution system of order $1 < \alpha < 2$ attracted many researchers and one can review the articles [10, 17, 25–33]. The study related to approximate controllability results for fractional Sobolev type Volterra-Fredholm integro-differential inclusions having order $1 < r < 2$ have not been discussed yet and it gives the additional motivation for writing this article.

Motivated by the theory developed in the works mentioned previously, our objective in this article is to discuss the approximate controllability of Sobolev type Volterra-Fredholm integro-differential inclusions of fractional order $r \in (1, 2)$ of the form

$${}^C D_r^\rho (Jz(\rho)) \in Az(\rho) + \mathcal{B}x(\rho) + E \left(\rho, z(\rho), \int_0^\rho e(\rho, s, z(s)) ds, \int_0^c h(\rho, s, z(s)) ds \right), \quad \rho \in V = [0, c], \quad (1.1)$$

$$z(0) = z_0, \quad z'(0) = z_1 \in \mathcal{Y}, \quad (1.2)$$

where $z(\cdot)$ takes values in \mathcal{Y} and \mathcal{Y} is a Hilbert space; ${}^C D_r^\rho$ represents fractional derivative in Caputo sense of order $r \in (1, 2)$, and the control function $x(\cdot) \in L^2(V, \mathcal{U})$, a Hilbert space of admissible control functions. A is the infinitesimal generator of a C_0 -cosine family $\{C(\rho)\}_{\rho \geq 0}$ on \mathcal{Y} . \mathcal{B} is a bounded linear operator from $\mathcal{U} \rightarrow \mathcal{Y}$. Here $D = \{(\rho, s) \in V \times V : s \leq \rho\}$, $e, h : D \times \mathcal{Y} \rightarrow \mathcal{Y}$ are continuous, and $E : V \times \mathcal{Y} \times \mathcal{Y} \times \mathcal{Y} \rightarrow 2^{\mathcal{Y}} \setminus \{\emptyset\}$ satisfying some conditions.

The arrangement of our article as follows: In Section 2, we recollect several fundamental definitions and few well-known results belong to fractional calculus and multivalued maps. In Section 3, we present the approximate controllability of (1.1)–(1.2) and in Section 4, we examine the system with concept of nonlocal conditions. In Section 5, the theory is validated with suitable example.

2 | BASIC FACTS

We now recollect few well-known results and definitions for proving our main results of this article.

Assume that $C(V, \mathcal{Y}) : V \rightarrow \mathcal{Y}$ be the Hilbert space of continuous functions along with $\|z\| = \sup_{\rho \in V} \|z(\rho)\|$, $z \in C(V, \mathcal{Y})$. Denote $D(A), R(A)$ be the domain and range of A . $\rho(A)$ stands for the resolvent set of A and we define the resolvent as follows:

$$R(\lambda, A) = (\lambda I - A)^{-1} \in L_c(\mathcal{Y}).$$

A measurable function $g : V \rightarrow \mathcal{Y}$ is Bochner's integrable provided $\|g\|$ is Lebesgue. Let $L^p(V, \mathcal{Y})$ ($p \geq 1$) be the Hilbert space of measurable functions endowed along with

$$\|g\|_p = \left(\int_V \|g(\rho)\|^p d\rho \right)^{\frac{1}{p}}.$$

We now present the linear operators $A : D(A) \subset \mathcal{Y} \rightarrow \mathcal{Y}$ and $J : D(A) \subset \mathcal{Y} \rightarrow \mathcal{Y}$ satisfy the following properties established in [34]:

- (E₁) $D(J) \subset D(A)$ and J is bijective.
- (E₂) The operators A and J are closed linear operators.
- (E₃) $J^{-1} : \mathcal{Y} \rightarrow D(J)$ is continuous.

Additionally, because of (E₁) and (E₂), J^{-1} is closed, by (E₃) and by referring the closed graph theorem, $AJ^{-1} : \mathcal{Y} \rightarrow \mathcal{Y}$ is bounded. Denote $\|J^{-1}\| = \tilde{J}_1$ and $\|J\| = \tilde{J}_2$.

By referring [1], we introduce definitions and remarks belongs to fractional calculus.

Definition 2.1 The integral of fractional order ν for the function $f : [0, \infty) \rightarrow \mathbb{R}$ with lower limit zero is given by

$$I^\nu f(\rho) = \frac{1}{\Gamma(\nu)} \int_0^\rho \frac{f(t)}{(\rho - t)^{1-\nu}} dt, \quad \rho > 0, \nu \in \mathbb{R}^+.$$

Definition 2.2 The R-L derivative of order ν for the function $f : [0, \infty) \rightarrow \mathbb{R}$ having lower limit zero is given by

$${}^L D^\nu f(\rho) = \frac{1}{\Gamma(n - \nu)} \frac{d^n}{d\rho^n} \int_0^\rho \frac{f^{(n)}(t)}{(\rho - t)^{\nu+1-n}} dt, \quad \rho > 0, n - 1 < \nu < n, \nu \in \mathbb{R}^+.$$

Definition 2.3 The Caputo derivative of order ν for the function f having lower limit zero is given by

$${}^C D^\nu f(\rho) = {}^L D^\nu \left(f(\rho) - \sum_{j=0}^{n-1} \frac{f^{(j)}(0)}{j!} \rho^j \right), \quad \rho > 0, n - 1 < \nu < n, \nu \in \mathbb{R}^+.$$

Remark 2.4 (1) If $f(\rho) \in C^n[0, \infty)$, then

$${}^C D^\nu f(\rho) = \frac{1}{\Gamma(n - \nu)} \int_0^\rho \frac{f^{(n)}(t)}{(\rho - t)^{\nu+1-n}} dt = I^{n-\nu} f^{(n)}(\rho), \quad \rho > 0, n - 1 < \nu < n.$$

(2) The above integrals are considered in Bochner’s sense if the function g is abstract with values belonged to \mathcal{Y} .

(3) The Caputo derivative of a constant function is equal to zero.

Definition 2.5 [35] The operator $\{C(\rho)\}_{\rho \in \mathbb{R}} : \mathcal{Y} \rightarrow \mathcal{Y}$ is called a strongly continuous cosine family if and only if

- (a) $C(t + \rho) + C(t - \rho) = 2C(t)C(\rho)$, for all $t, \rho \in \mathbb{R}$;
- (b) $C(\rho)z$ is strongly continuous on \mathbb{R} for every $z \in \mathcal{Y}$;
- (c) $C(0) = I$.

Assume that the sine family associated with $\{C(\rho)\}_{\rho \in \mathbb{R}}$ is $\{S(\rho)\}_{\rho \in \mathbb{R}}$, where

$$S(\rho)z = \int_0^\rho C(t)z dt, \quad z \in \mathcal{Y}, \rho \in \mathbb{R}. \tag{2.1}$$

Further, if

$$\left(Az = \left. \frac{d^2}{d\rho^2} C(\rho)z \right|_{\rho=0}, \text{ for all } z \in D(A), \right.$$

where

$$D(A) = \{z \in \mathcal{Y} : C(\rho)z \in C^2(\mathbb{R}, \mathcal{Y})\}.$$

Determine

$$G = \{z \in \mathcal{Y} : C(\rho)z \in C^1(\mathbb{R}, \mathcal{Y})\}.$$

Clearly, A is a closed dense operator in \mathcal{Y} , there exists a constant $P \geq 1$ if $\|N(\rho)\|_{L_c(\mathcal{Y})} \leq P$, where $\rho \geq 0$. Let us fix $a = \frac{r}{2}$ for $r \in (1, 2)$ which is discussed in [25, 33].

Definition 2.6 The upper semicontinuous (u.s.c) operator \mathcal{K} on \mathcal{Y} provided for all $z_0 \in \mathcal{Y}$ and $\mathcal{K}(z_0)$ is a nonempty closed subset of \mathcal{Y} , for each open set \mathcal{E} of \mathcal{Y} including $\mathcal{K}(z_0)$, there exists an open neighborhood \mathcal{W} of z_0 with

$$\mathcal{K}(\mathcal{W}) \subseteq \mathcal{E}.$$

Definition 2.7 \mathcal{K} is completely continuous if $\mathcal{K}(\mathcal{E})$ is relatively compact for each bounded subset \mathcal{E} of \mathcal{Y} . If \mathcal{K} is completely continuous and nonempty, then \mathcal{K} is u.s.c., if and only if \mathcal{K} has a closed graph. \mathcal{K} has a fixed point such that there exists $z \in \mathcal{Y}$ such that $z \in \mathcal{K}(z)$.

The fractional system (1.1)–(1.2) is similar to the following system

$$\begin{aligned} z(\rho) &= J^{-1}z_0J + J^{-1}z_1J\rho \\ &+ \frac{1}{\Gamma(r)} \int_0^\rho (\rho - t)^{r-1} J^{-1} \left[Az(t) + E \left(t, z(t), \int_0^t e(t, s, z(s)) ds, \int_0^c h(t, s, z(s)) ds \right) \right] dt \\ &+ \frac{1}{\Gamma(r)} \int_0^\rho (\rho - t)^{r-1} J^{-1} \mathcal{Y} x(t) dt. \end{aligned} \tag{2.2}$$

In view [36] and using Laplace transform, we introduce the solution of (1.1)–(1.2).

Definition 2.8 [36] A function $z \in C = C(V, \mathcal{Y})$ is called a mild solution of (1.1)–(1.2) if $z(0) = z_0, z'(0) = z_1, x(\cdot) \in L^2(V, \mathcal{U})$ and there exists $g \in L^1(V, \mathcal{Y})$ such that $g(\rho) \in E(\rho, z(\rho), \int_0^\rho e(\rho, s, z(s)) ds, \int_0^c h(\rho, s, z(s)) ds)$ on a.e. $\rho \in V$ and

$$\begin{aligned} z(\rho) &= J^{-1}M_a(\rho)Jz_0 + J^{-1}W_a(\rho)Jz_1 + \int_0^\rho (\rho - t)^{a-1} J^{-1}Q_a(\rho - t) \mathcal{B}x(t) dt \\ &+ \int_0^\rho (\rho - t)^{a-1} J^{-1}Q_a(\rho - t) g(t) dt, \end{aligned} \tag{2.3}$$

where

$$M_a(\rho) = \int_0^\infty S_a(\rho) C(\rho^a \rho) d\rho, \quad W_a(\rho) = \int_0^\rho M_a(t) dt, \quad Q_a(\rho) = \int_0^\infty a\rho S_a(\rho) S(\rho^a \rho) d\rho,$$

$$S_a(\rho) = \frac{1}{a} \rho^{-1-\frac{1}{a}} \zeta_a \left(\rho^{-\frac{1}{a}} \right), \quad \zeta_a(\rho) = \frac{1}{\pi} \sum_{n=1}^\infty (-1)^{n-1} \rho^{-na-1} \frac{\Gamma(na+1)}{n!} \sin(n\pi a), \quad \rho \in (0, \infty),$$

where $S_a(\cdot)$ is a probability density function defined on $(0, \infty)$ such that

$$S_a(\rho) \geq 0 \text{ where } \rho \in (0, \infty) \text{ also } \int_0^\infty S_a(\rho) d\rho = 1.$$

Remark 2.9 Clearly for $n \in [0, 1]$

$$\int_0^\infty \rho^n S_a(\rho) d\rho = \int_0^\infty \rho^{-an} \zeta(\rho) d\rho = \frac{\Gamma(1+n)}{\Gamma(1+an)}.$$

Lemma 2.10 [25]. $M_a(\rho)$, $W_a(\rho)$ and $Q_a(\rho)$ satisfy the following properties:

- (a) for all $\rho \geq 0$, $M_a(\rho)$, $W_a(\rho)$ and $Q_a(\rho)$ are linear and bounded;
- (b) $\forall z \in \mathcal{Y}$ and for all $\rho \geq 0$, we have

$$\|M_a(\rho)z\| \leq P\|z\|, \quad \|W_a(\rho)z\| \leq P\|z\|\rho, \quad \|Q_a(\rho)z\| \leq \frac{P}{\Gamma(2a)}\|z\|\rho^a;$$

- (c) $\{M_a(\rho), \rho \geq 0\}$, $\{W_a(\rho), \rho \geq 0\}$ and $\{\rho^{a-1}Q_a(\rho), \rho \geq 0\}$ are strongly continuous.

Lemma 2.11 [35].

- (i) If $z \in G$, subsequently $S(\rho)z \in D(A)$, also; $\frac{d}{d\rho}C(\rho)z = AS(\rho)z$;
- (ii) There exists $P \geq 1$, $\omega \geq 0$ such that $\|C(\rho)\|_{L_c(\mathcal{Y})} \leq Pe^{\omega|\rho|}$, for all $\rho \in \mathbb{R}$;
- (iii) $\|S(\rho + \hbar) - S(\rho)\|_{L_c(\mathcal{Y})} \leq P \int_{\rho}^{\rho+\hbar} e^{\omega|t|} dt$ for all $\rho + \hbar, \rho \in \mathbb{R}$.

Lemma 2.12 Assume that $\{C(\rho)\}_{\rho \in \mathbb{R}}$ on \mathcal{Y} , then

$$\lim_{\rho \rightarrow 0} \frac{1}{\rho} S(\rho)z = z$$

for some $z \in \mathcal{Y}$.

Lemma 2.13 [35] Suppose $\{C(\rho)\}_{\rho \in \mathbb{R}}$ on \mathcal{Y} satisfying $\|C(\rho)\|_{L_c(\mathcal{Y})} \leq Pe^{\omega|\rho|}$, $\rho \in \mathbb{R}$. Subsequently for $Re\Lambda > \omega$, $\Lambda^2 \in \rho(A)$. Additionally

$$\Lambda R(\Lambda^2; A)z = \int_0^\infty e^{-\Lambda \rho} C(\rho)z d\rho, \quad R(\Lambda^2; A)z = \int_0^\infty e^{-\Lambda \rho} S(\rho)z d\rho, \quad \text{for } z \in \mathcal{Y}.$$

We present the essential operators and some useful results as follows:

$$\Gamma_0^c = \int_0^c (c-i)^{a-1} J^{-1} Q_a(c-i) \mathcal{B} \mathcal{B}^* J^{-1} Q_a^*(c-i) dt : \mathcal{Y} \rightarrow \mathcal{Y},$$

$$R(\mu, \Gamma_0^c) = (\mu I + \Gamma_0^c)^{-1} : \mathcal{Y} \rightarrow \mathcal{Y},$$

where \mathcal{B}^* , $Q_a^*(c)$ stand for adjoints \mathcal{B} and $Q_a(c)$. Now, we come to an end that Γ_0^c is bounded.

We start with the following assumption:

H₀ $\mu R(\mu, \Gamma_0^c) \rightarrow 0$ as $\mu \rightarrow 0^+$ in the strong operator topology.

In view of [22], **H₀** holds if and only if the linear fractional system

$$\begin{cases} {}^c D_{0+}^\alpha (Jz(\rho)) \in Az(\rho) + (\mathcal{B}x)(\rho), & \rho \in V, \\ z(0) = z_0, \quad z'(0) = z_1 \in \mathcal{Y}, \end{cases} \tag{2.4}$$

is approximately controllable on V .

Lemma 2.14 [36]. Suppose $BCC(\mathcal{Y})$ be the set of all nonempty, bounded, closed and convex subset of \mathcal{Y} , V be a compact real interval. Let E be a multivalued map satisfying $E : V \times \mathcal{Y} \rightarrow BCC(\mathcal{Y})$ is measurable to ρ for every fixed $z \in \mathcal{Y}$, u.s.c. to z for every $\rho \in V$, and for every $z \in C$,

$$S_{E,z} = \left\{ g \in L^1(V, \mathcal{Y}) : g(\rho) \in E\left(\rho, z(\rho), \int_0^\rho e(\rho, s, z(s)) ds, \int_0^c h(\rho, s, z(s)) ds\right), \rho \in V \right\}$$

is nonempty. Suppose \mathcal{M} be linear continuous from $L^1(V, \mathcal{Y}) \rightarrow C$, then

$$\mathcal{M} \circ S_E : C \rightarrow BCC(C), \quad z \rightarrow (\mathcal{M} \circ S_E)(z) = \mathcal{M}(S_{E,z}),$$

is a closed graph operator in $C \rightarrow C$.

Lemma 2.15 *Suppose H be a closed, bounded and convex nonempty subset H of \mathcal{Y} . Assume $D : H \rightarrow 2^{\mathcal{Y}} \setminus \{\emptyset\}$ is upper semicontinuous with closed, convex values such that $D(H) \subset H$ and $D(H)$ is compact, then D has a fixed point.*

3 | RESULTS ON APPROXIMATE CONTROLLABILITY

We here particularly focusing on approximate controllability of (1.1)–(1.2). Let us introduce the important assumptions to discuss the primary theorems.

H₁ For $\rho \geq 0$, $\{C(\rho)\}$ is compact.

H₂ The function $E : V \times \mathcal{Y} \times \mathcal{Y} \times \mathcal{Y} \rightarrow BCC(\mathcal{Y})$ is measurable to ρ , for all $z \in \mathcal{Y}$, u.s.c. to z , for all $\rho \in V$, and for all $z \in C$

$$S_{E,z} = \left\{ g \in L^1(V, \mathcal{Y}) : g(\rho) \in E(\rho, z(\rho), \int_0^\rho e(\rho, s, z(s)) ds, \int_0^c h(\rho, s, z(s)) ds), \rho \in V \right\},$$

is nonempty.

H₃ For each $(\rho, s) \in D$, the functions $e(\rho, s, \cdot), h(\rho, s, \cdot) : \mathcal{Y} \rightarrow \mathcal{Y}$ are continuous and for all $z \in \mathcal{Y}$, $e(\cdot, \cdot, z), h(\cdot, \cdot, z) : D \rightarrow \mathcal{Y}$ are strongly measurable.

H₄ For $\alpha > 0, z \in C$ along with $\|z\|_C \leq \alpha$, there exists $\nu \in (0, b)$ and $L_{g,\alpha}(\cdot) \in L^{\frac{1}{\nu}}(V, \mathbb{R}^+)$ such that

$$\sup \left\{ \|g\| : g(\rho) \in E(\rho, z(\rho), \int_0^\rho e(\rho, s, z(s)) ds, \int_0^c h(\rho, s, z(s)) ds) \right\} \leq L_{g,\alpha}(\rho),$$

for almost everywhere $\rho \in V$.

H₅ The function $t \rightarrow (\rho - t)^{a-1} L_{g,\alpha}(t) \in L^1(V, \mathbb{R}^+)$ and there exists a constant $\lambda > 0$ such that

$$\liminf_{\alpha \rightarrow \infty} \frac{\int_0^\rho (\rho - t)^{a-1} L_{g,\alpha}(t) dt}{\alpha} = \lambda < +\infty.$$

For discussing the approximate controllability of (1.1)–(1.2), if for all $\mu > 0$, there exists $z(\cdot) \in C$ such that

$$\begin{aligned} z(\rho) &= J^{-1} M_a(\rho) J z_0 + J^{-1} W_a(\rho) J z_1 + \int_0^\rho (\rho - t)^{a-1} J^{-1} Q_a(\rho - t) g(t) dt \\ &+ \int_0^\rho (\rho - t)^{a-1} J^{-1} Q_a(\rho - t) \mathcal{B} x(t) dt, \quad g \in S_{E,z}, \end{aligned} \quad (3.1)$$

$$x(\rho) = \mathcal{B}^* J^{-1} Q_a^*(c - \rho) R(\mu, \Gamma_0^c) q(z(\cdot)), \quad (3.2)$$

where

$$q(z(\cdot)) = z_c - J^{-1} M_a(c) J z_0 - J^{-1} W_a(c) J z_1 - \int_0^c (c - t)^{a-1} J^{-1} Q_a(c - t) g(t) dt.$$

Theorem 3.1 *Assume **H₀**–**H₅** holds, subsequently (1.1)–(1.2) has a solution on V provided*

$$\frac{P\tilde{J}_1}{\Gamma(2a)} \left[1 + \frac{1}{\mu} \left(\frac{P\tilde{J}_1 P_B}{\Gamma(2a)} \right)^2 \frac{c^{2a}}{2a} \right] \lambda < 1, \quad (3.3)$$

where $P_B = \|\mathcal{B}\|$.

Proof. The fundamental point is to discover conditions for solvability of (3.1) and (3.2) for $\mu > 0$. Now, we prove $\mathcal{R} : C \rightarrow 2^C$ determined by

$$\mathcal{R}(z) = \left\{ z \in C; m(\rho) = J^{-1}M_a(\rho)Jz_0 + J^{-1}W_a(\rho)Jz_1 + \int_0^\rho (\rho - t)^{a-1}J^{-1}Q_a(\rho - t)g(t)dt + \int_0^\rho (\rho - t)^{a-1}J^{-1}Q_a(\rho - t)\mathcal{B}x(t)dt, g \in S_{E,z} \right\},$$

has a fixed point. We subdivide our proof for simplicity:

Step 1: For all $\mu > 0$, $\mathcal{R}(z)$ is convex for all $z \in C$. Suppose $m_1, m_2 \in C$, then there exists $g_1, g_2 \in S_{E,z}$ such that $\rho \in V$, we have

$$\begin{aligned} m_i(\rho) &= J^{-1}M_a(\rho)Jz_0 + J^{-1}W_a(\rho)Jz_1 + \int_0^\rho (\rho - t)^{a-1}J^{-1}Q_a(\rho - t)g_i(t)dt \\ &+ \int_0^\rho (\rho - t)^{a-1}J^{-1}Q_a(\rho - t)\mathcal{B}\mathcal{B}^*J^{-1}Q_a^*(c - \rho)R(\mu, \Gamma_0^c)[z_c - J^{-1}M_a(c)Jz_0 - J^{-1}W_a(c)Jz_1 \\ &- \int_0^c (c - \varphi)^{a-1}J^{-1}Q_a(c - \varphi)g_i(\varphi)d\varphi](t)dt, i = 1, 2. \end{aligned}$$

Let $0 \leq \beta \leq 1$, then for each $\rho \in V$ we have

$$\begin{aligned} (\beta m_1 + (1 - \beta)m_2)(\rho) &= J^{-1}M_a(\rho)Jz_0 + J^{-1}W_a(\rho)Jz_1 + \int_0^\rho (\rho - t)^{a-1}J^{-1}Q_a(\rho - t)[\beta g_1(t) \\ &+ (1 - \beta)g_2(t)]dt + \int_0^\rho (\rho - t)^{a-1}J^{-1}Q_a(\rho - t)\mathcal{B}\mathcal{B}^*J^{-1}Q_a^*(c - \rho)R(\mu, \Gamma_0^c)[z_c - J^{-1}M_a(c)Jz_0 \\ &- J^{-1}W_a(c)Jz_1 - \int_0^c (c - \varphi)^{a-1}J^{-1}Q_a(c - \varphi)[\beta g_1(\varphi) + (1 - \beta)g_2(\varphi)]d\varphi](t)dt. \end{aligned}$$

Since $S_{E,z}$ is convex, $\beta m_1 + (1 - \beta)m_2 \in S_{E,z}$. Hence $\beta m_1 + (1 - \beta)m_2 \in \mathcal{R}(z)$.

Step 2: On the space C , consider $Q_\alpha = \{z \in C : \|z\|_C \leq \alpha, 0 \leq \rho \leq c\}$, $\alpha > 0$. Clearly, Q_α is bounded, closed and convex set of C . For $\mu > 0$, our property is that there exists $\alpha > 0$ such that

$$\mathcal{R}(Q_\alpha) \subset Q_\alpha.$$

If not, then for all $\alpha > 0$, there exists $z^\alpha \in Q_\alpha$, but $\mathcal{R}(z^\alpha) \notin Q_\alpha$, i.e.,

$$\|\mathcal{R}(z^\alpha)\|_C \equiv \sup \{\|m^\alpha\|_C : m^\alpha \in (\mathcal{R}z^\alpha)\} > \alpha$$

and

$$\begin{aligned} m^\alpha(\rho) &= J^{-1}M_a(\rho)Jz_0 + J^{-1}W_a(\rho)Jz_1 + \int_0^\rho (\rho - t)^{a-1}J^{-1}Q_a(\rho - t)g^\alpha(t)dt \\ &+ \int_0^\rho (\rho - t)^{a-1}J^{-1}Q_a(\rho - t)\mathcal{B}x^\alpha(t)dt, \end{aligned}$$

for some $g^\alpha \in S_{E,z^\alpha}$.

Using assumptions **H₃** and Lemma 2.10, we have

$$\begin{aligned} \|x^\alpha(\rho)\| &= \|\mathcal{B}^*J^{-1}Q_a^*(c - \rho)R(\mu, \Gamma_0^c)q(z(\cdot))\| \\ &= \|\mathcal{B}^*J^{-1}Q_a^*(c - \rho)R(\mu, \Gamma_0^c)[z_c - J^{-1}M_a(c)Jz_0 - J^{-1}W_a(c)Jz_1 \\ &- \int_0^c (c - t)^{a-1}J^{-1}Q_a(c - t)g^\alpha(t)dt]\| \end{aligned}$$

$$\begin{aligned}
&\leq \|J^{-1}\| \|\mathcal{B}^*\| \|\mathcal{Q}_a^*(c-\varrho)\| \|R(\mu, \Gamma_0^c)\| \| [z_c - J^{-1}M_a(c)Jz_0 - J^{-1}W_a(c)Jz_1 \\
&\quad - \int_0^c (c-i)^{a-1} J^{-1}Q_a(c-i)g^\alpha(i)di] \| \\
&\leq P_B \tilde{J}_1 \left(\frac{P}{\Gamma(2a)} \right) \frac{1}{\mu} [\|z_c\| + \|J^{-1}M_a(c)Jz_0\| + \|J^{-1}W_a(c)Jz_1\| \\
&\quad + \int_0^c (c-i)^{a-1} \|J^{-1}Q_a(c-i)g^\alpha(i)\|di] \\
&\leq \frac{1}{\mu} \frac{P\tilde{J}_1 P_B}{\Gamma(2a)} \left[\|z_c\| + \tilde{J}_1 P \tilde{J}_2 \|z_0\| + \tilde{J}_1 P c \tilde{J}_2 \|z_1\| + \frac{P\tilde{J}_1}{\Gamma(2a)} \int_0^c (c-i)^{2a-1} L_{g,\alpha}(i)di \right]
\end{aligned}$$

For such $\mu > 0$, we prove that

$$\begin{aligned}
\alpha < \|(\mathcal{R}z^\alpha)(\varrho)\| &\leq \|J^{-1}M_a(\varrho)Jz_0\| + \|J^{-1}W_a(\varrho)Jz_1\| + \int_0^\varrho (\varrho-i)^{a-1} \|J^{-1}Q_a(\varrho-i)g^\alpha(i)\|di \\
&\quad + \int_0^\varrho (\varrho-i)^{a-1} \|J^{-1}Q_a(\varrho-i)\mathcal{B}x^\alpha(i)\|di \\
&\leq \tilde{J}_1 P \tilde{J}_2 \|z_0\| + \tilde{J}_1 P \rho \tilde{J}_2 \|z_1\| + \frac{P\tilde{J}_1}{\Gamma(2a)} \int_0^\varrho (\varrho-i)^{2a-1} L_{g,\alpha}(i)di \\
&\quad + \frac{P\tilde{J}_1 P_B}{\Gamma(2a)} \int_0^\varrho (\varrho-i)^{2a-1} \frac{1}{\mu} \frac{\tilde{J}_1 P P_B}{\Gamma(2a)} [\|z_c\| + \tilde{J}_1 P \tilde{J}_2 \|z_0\| + \tilde{J}_1 P c \tilde{J}_2 \|z_1\| \\
&\quad + \frac{P\tilde{J}_1}{\Gamma(2a)} \int_0^c (c-i)^{2a-1} L_{g,\alpha}(i)di] di \\
&\leq \tilde{J}_1 P \tilde{J}_2 \|z_0\| + \tilde{J}_1 P \rho \tilde{J}_2 \|z_1\| + \frac{P\tilde{J}_1}{\Gamma(2a)} \int_0^\varrho (\varrho-i)^{2a-1} L_{g,\alpha}(i)di \\
&\quad + \frac{1}{\mu} \left(\frac{P\tilde{J}_1 P_B}{\Gamma(2a)} \right)^2 \frac{c^{2a}}{2a} \left[\|z_c\| + \tilde{J}_1 P \tilde{J}_2 \|z_0\| + \tilde{J}_1 P c \tilde{J}_2 \|z_1\| + \frac{P\tilde{J}_1}{\Gamma(2a)} \int_0^c (c-i)^{2a-1} L_{g,\alpha}(i)di \right]. \tag{3.4}
\end{aligned}$$

Dividing the Equation (3.4) by α , applying limit as $\alpha \rightarrow \infty$ to the above inequality and utilizing **H₄**, we obtain

$$\frac{P\tilde{J}_1}{\Gamma(2a)} \left[1 + \frac{1}{\mu} \left(\frac{P\tilde{J}_1 P_B}{\Gamma(2a)} \right)^2 \frac{c^{2a}}{2a} \right] \lambda \geq 1,$$

which contradicts our assumption. Hence $\mu > 0$, there exists $\alpha > 0$ such that \mathcal{R} maps $\mathcal{Q}_\alpha \rightarrow \mathcal{Q}_\alpha$.

Step 3: \mathcal{R} mapping bounded sets into equicontinuous sets of C .

For all $m \in \mathcal{R}(z)$ and $z \in \mathcal{Q}_\alpha$, there exists $g \in \mathcal{S}_{E,z}$, we define

$$\begin{aligned}
m(\varrho) &= J^{-1}M_a(\varrho)Jz_0 + J^{-1}W_a(\varrho)Jz_1 + \int_0^\varrho (\varrho-i)^{a-1} J^{-1}Q_a(\varrho-i)g(i)di \\
&\quad + \int_0^\varrho (\varrho-i)^{a-1} J^{-1}Q_a(\varrho-i)\mathcal{B}x(i)di.
\end{aligned}$$

Let $0 < \epsilon < \varrho < \varrho + h \leq c$.

Then,

$$\|m(\varrho+h) - m(\varrho)\| \leq \|J^{-1}[M_a(\varrho+h) - M_a(\varrho)]Jz_0\| + \|J^{-1}[W_a(\varrho+h) - W_a(\varrho)]Jz_1\|$$

$$\begin{aligned}
 & + \int_{\rho}^{\rho+h} (\rho+h-i)^{a-1} \|J^{-1}Q_a(\rho+h-i)g(i)\|di \\
 & + \int_{\rho-\epsilon}^{\rho} (\rho+h-i)^{a-1} \| [J^{-1}Q_a(\rho+h-i) - J^{-1}Q_a(\rho-i)] g(i)\|di \\
 & + \int_{\rho-\epsilon}^{\rho} [(\rho+h-i)^{a-1} - (\rho-i)^{a-1}] \|J^{-1}Q_a(\rho-i)g(i)\|di \\
 & + \int_0^{\rho-\epsilon} (\rho+h-i)^{a-1} \| [J^{-1}Q_a(\rho+h-i) - J^{-1}Q_a(\rho-i)] g(i)\|di \\
 & + \int_0^{\rho-\epsilon} [(\rho+h-i)^{a-1} - (\rho-i)^{a-1}] \|J^{-1}Q_a(\rho-i)g(i)\|di \\
 & + \int_{\rho}^{\rho+h} (\rho+h-i)^{a-1} \|J^{-1}Q_a(\rho+h-i)\mathcal{B}x(i)\|di \\
 & + \int_{\rho-\epsilon}^{\rho} (\rho+h-i)^{a-1} \| [J^{-1}Q_a(\rho+h-i) - J^{-1}Q_a(\rho-i)] \mathcal{B}x(i)\|di \\
 & + \int_{\rho-\epsilon}^{\rho} [(\rho+h-i)^{a-1} - (\rho-i)^{a-1}] \|J^{-1}Q_a(\rho-i)\mathcal{B}x(i)\|di \\
 & + \int_0^{\rho-\epsilon} (\rho+h-i)^{a-1} \| [J^{-1}Q_a(\rho+h-i) - J^{-1}Q_a(\rho-i)] \mathcal{B}x(i)\|di \\
 & + \int_0^{\rho-\epsilon} [(\rho+h-i)^{a-1} - (\rho-i)^{a-1}] \|J^{-1}Q_a(\rho-i)\mathcal{B}x(i)\|di \\
 & = \sum_{i=1}^{12} \mathcal{O}_i.
 \end{aligned}$$

Let $b = \frac{2a-1}{1-\nu} \in (-1, 0)$. By applying \mathbf{H}_1 , \mathbf{H}_3 and Lemma 2.10 for $\mathcal{O}_3, \mathcal{O}_4, \mathcal{O}_5, \mathcal{O}_6$ and \mathcal{O}_7 , we have

$$\begin{aligned}
 \mathcal{O}_3 & \leq \frac{P\tilde{J}_1}{\Gamma(2a)} \int_{\rho}^{\rho+h} (\rho+h-i)^{2a-1} \|g(i)\|di \\
 & \leq \frac{P\tilde{J}_1}{\Gamma(2a)} \int_{\rho}^{\rho+h} (\rho+h-i)^{2a-1} L_{g,\alpha}(i)di \\
 & \leq \frac{P\tilde{J}_1}{\Gamma(2a)} \left(\int_{\rho}^{\rho+h} (\rho+h-i)^{\frac{2a-1}{1-\nu}} di \right)^{1-\nu} \|L_{g,\alpha}\|_{L^{\frac{1}{\nu}}(\nu, \mathbb{R}^+)} \\
 & \leq \frac{P\tilde{J}_1}{\Gamma(2a)} \left[\frac{h^{(b+1)(1-\nu)}}{(b+1)^{1-\nu}} \right] \|L_{g,\alpha}\|_{L^{\frac{1}{\nu}}(\nu, \mathbb{R}^+)},
 \end{aligned}$$

$$\begin{aligned}
 \mathcal{O}_4 & \leq \frac{2P\tilde{J}_1}{\Gamma(2a)} \int_{\rho-\epsilon}^{\rho} (\rho+h-i)^{2a-1} \|g(i)\|di \\
 & \leq \frac{2P\tilde{J}_1}{\Gamma(2a)} \int_{\rho-\epsilon}^{\rho} (\rho+h-i)^{2a-1} L_{g,\alpha}(i)di \\
 & \leq \frac{2P\tilde{J}_1}{\Gamma(2a)} \left(\int_{\rho-\epsilon}^{\rho} (\rho+h-i)^{\frac{2a-1}{1-\nu}} di \right)^{1-\nu} \|L_{g,\alpha}\|_{L^{\frac{1}{\nu}}(\nu, \mathbb{R}^+)}
 \end{aligned}$$

$$\leq \frac{2P\tilde{J}_1}{\Gamma(2a)} \left[\frac{\epsilon^{(b+1)(1-\nu)}}{(b+1)^{1-\nu}} \right] \|L_{g,\alpha}\|_{L^{\frac{1}{\nu}}(\nu, \mathbb{R}^+)},$$

$$\begin{aligned} \mathcal{O}_5 &\leq \frac{P\tilde{J}_1}{\Gamma(2a)} \int_{\rho-\epsilon}^{\rho} [(\rho+h-i)^{2a-1} - (\rho-i)^{2a-1}] \|g(i)\| di \\ &\leq \frac{P\tilde{J}_1}{\Gamma(2a)} \left(\int_{\rho-\epsilon}^{\rho} [(\rho+h-i)^{2a-1} - (\rho-i)^{2a-1}]^{\frac{1}{1-\nu}} di \right)^{1-\nu} \|L_{g,\alpha}\|_{L^{\frac{1}{\nu}}(\nu, \mathbb{R}^+)} \\ &\leq \frac{P\tilde{J}_1}{\Gamma(2a)} \left[\frac{2h^{(b+1)(1-\nu)}}{(b+1)^{1-\nu}} \right] \|L_{g,\alpha}\|_{L^{\frac{1}{\nu}}(\nu, \mathbb{R}^+)}, \end{aligned}$$

$$\begin{aligned} \mathcal{O}_6 &\leq \sup_{i \in [0, \rho-\epsilon]} \|J^{-1}Q_a(\rho+h-i) - J^{-1}Q_a(\rho-i)\| \int_0^{\rho-\epsilon} (\rho+h-i)^{2a-1} \|g(i)\| di \\ &\leq \sup_{i \in [0, \rho-\epsilon]} \|J^{-1}Q_a(\rho+h-i) - J^{-1}Q_a(\rho-i)\| \int_0^{\rho-\epsilon} (\rho+h-i)^{2a-1} L_{g,\alpha}(i) di \\ &\leq \sup_{i \in [0, \rho-\epsilon]} \|J^{-1}Q_a(\rho+h-i) - J^{-1}Q_a(\rho-i)\| \left(\int_0^{\rho-\epsilon} (\rho+h-i)^{\frac{2a-1}{1-\nu}} di \right)^{1-\nu} \|L_{g,\alpha}\|_{L^{\frac{1}{\nu}}(\nu, \mathbb{R}^+)} \\ &\leq \sup_{i \in [0, \rho-\epsilon]} \|J^{-1}Q_a(\rho+h-i) - J^{-1}Q_a(\rho-i)\| \frac{[(\rho+h)^{b+1} - (\rho+\epsilon)^{b+1}]^{1-\nu}}{(b+1)^{1-\nu}} \|L_{g,\alpha}\|_{L^{\frac{1}{\nu}}(\nu, \mathbb{R}^+)}, \end{aligned}$$

$$\begin{aligned} \mathcal{O}_7 &\leq \frac{P\tilde{J}_1}{\Gamma(2a)} \int_0^{\rho-\epsilon} [(\rho+h-i)^{2a-1} - (\rho-i)^{2a-1}] \|g(i)\| di \\ &\leq \frac{P\tilde{J}_1}{\Gamma(2a)} \int_0^{\rho-\epsilon} [(\rho+h-i)^{2a-1} - (\rho-i)^{2a-1}] L_{g,\alpha}(i) di \\ &\leq \frac{P\tilde{J}_1}{\Gamma(2a)} \left(\int_0^{\rho-\epsilon} [(\rho+h-i)^{2a-1} - (\rho-i)^{2a-1}]^{\frac{1}{1-\nu}} di \right)^{1-\nu} \|L_{g,\alpha}\|_{L^{\frac{1}{\nu}}(\nu, \mathbb{R}^+)} \\ &\leq \frac{P\tilde{J}_1}{\Gamma(2a)} \left[\frac{2h^{(b+1)(1-\nu)}}{(b+1)^{1-\nu}} \right] \|L_{g,\alpha}\|_{L^{\frac{1}{\nu}}(\nu, \mathbb{R}^+)}, \end{aligned}$$

For $\mathcal{O}_8, \mathcal{O}_9, \mathcal{O}_{10}, \mathcal{O}_{11}$ and \mathcal{O}_{12} , using the $\mathbf{H}_1, \mathbf{H}_3$ and Lemma 2.10

$$\begin{aligned} \mathcal{O}_8 &\leq \frac{P\tilde{J}_1}{\Gamma(2a)} \int_{\rho}^{\rho+h} (\rho+h-i)^{2a-1} \|\mathcal{B}x(i)\| di \\ &\leq \frac{P\tilde{J}_1 P_B}{\Gamma(2a)} \int_{\rho}^{\rho+h} (\rho+h-i)^{2a-1} \|x(i)\| di \\ &\leq \frac{P\tilde{J}_1 P_B}{\Gamma(2a)} \left(\int_{\rho}^{\rho+h} (\rho+h-i)^{\frac{2a-1}{1-\nu}} di \right)^{1-\nu} \|x\| \\ &\leq \frac{P\tilde{J}_1 P_B}{\Gamma(2a)} \left[\frac{h^{(b+1)(1-\nu)}}{(b+1)^{1-\nu}} \right] \|x\|, \end{aligned}$$

$$\begin{aligned} \mathcal{O}_9 &\leq \frac{2P\tilde{J}_1}{\Gamma(2a)} \int_{\rho-\epsilon}^{\rho} (\rho+h-i)^{2a-1} \|\mathcal{B}x(i)\| di \\ &\leq \frac{2P\tilde{J}_1 P_B}{\Gamma(2a)} \int_{\rho-\epsilon}^{\rho} (\rho+h-i)^{2a-1} \|x(i)\| di \end{aligned}$$

$$\begin{aligned} &\leq \frac{2P\tilde{J}_1P_B}{\Gamma(2a)} \left(\int_{\rho-\epsilon}^{\rho} (\rho+h-i)^{\frac{2a-1}{1-\nu}} dt \right)^{1-\nu} \|x\| \\ &\leq \frac{2P\tilde{J}_1P_B}{\Gamma(2a)} \left[\frac{\epsilon^{(b+1)(1-\nu)}}{(b+1)^{1-\nu}} \right] \|x\|, \end{aligned}$$

$$\begin{aligned} \mathcal{O}_{10} &\leq \frac{P\tilde{J}_1}{\Gamma(2a)} \int_{\rho-\epsilon}^{\rho} [(\rho+h-i)^{2a-1} - (\rho-i)^{2a-1}] \|\mathcal{B}x(t)\| dt \\ &\leq \frac{P\tilde{J}_1P_B}{\Gamma(2a)} \int_{\rho-\epsilon}^{\rho} [(\rho+h-i)^{2a-1} - (\rho-i)^{2a-1}] \|x(t)\| dt \\ &\leq \frac{P\tilde{J}_1P_B}{\Gamma(2a)} \left(\int_{\rho-\epsilon}^{\rho} [(\rho+h-i)^{2a-1} - (\rho-i)^{2a-1}]^{\frac{1}{1-\nu}} dt \right)^{1-\nu} \|x\| \\ &\leq \frac{P\tilde{J}_1P_B}{\Gamma(2a)} \left[\frac{2h^{(b+1)(1-\nu)}}{(b+1)^{1-\nu}} \right] \|x\|, \end{aligned}$$

$$\begin{aligned} \mathcal{O}_{11} &\leq \sup_{t \in [0, \rho-\epsilon]} \|J^{-1}Q_a(\rho+h-i) - J^{-1}Q_a(\rho-i)\| \int_0^{\rho-\epsilon} (\rho+h-i)^{2a-1} \|\mathcal{B}x(t)\| dt \\ &\leq P_B \sup_{t \in [0, \rho-\epsilon]} \|J^{-1}Q_a(\rho+h-i) - J^{-1}Q_a(\rho-i)\| \int_0^{\rho-\epsilon} (\rho+h-i)^{2a-1} \|x(t)\| dt \\ &\leq P_B \sup_{t \in [0, \rho-\epsilon]} \|J^{-1}Q_a(\rho+h-i) - J^{-1}Q_a(\rho-i)\| \left(\int_0^{\rho-\epsilon} (\rho+h-i)^{\frac{2a-1}{1-\nu}} dt \right)^{1-\nu} \|x\| \\ &\leq P_B \sup_{t \in [0, \rho-\epsilon]} \|J^{-1}Q_a(\rho+h-i) - J^{-1}Q_a(\rho-i)\| \frac{[(\rho+h)^{b+1} - (\rho+\epsilon)^{b+1}]^{1-\nu}}{(b+1)^{1-\nu}} \|x\|, \end{aligned}$$

$$\begin{aligned} \mathcal{O}_{12} &\leq \frac{P\tilde{J}_1}{\Gamma(2a)} \int_0^{\rho-\epsilon} [(\rho+h-i)^{2a-1} - (\rho-i)^{2a-1}] \|\mathcal{B}x(t)\| dt \\ &\leq \frac{P\tilde{J}_1P_B}{\Gamma(2a)} \int_0^{\rho-\epsilon} [(\rho+h-i)^{2a-1} - (\rho-i)^{2a-1}] \|x(t)\| dt \\ &\leq \frac{P\tilde{J}_1P_B}{\Gamma(2a)} \left(\int_0^{\rho-\epsilon} [(\rho+h-i)^{2a-1} - (\rho-i)^{2a-1}]^{\frac{1}{1-\nu}} dt \right)^{1-\nu} \|x\| \\ &\leq \frac{P\tilde{J}_1P_B}{\Gamma(2a)} \left[\frac{2h^{(b+1)(1-\nu)}}{(b+1)^{1-\nu}} \right] \|x\|. \end{aligned}$$

It is easy to verify \mathcal{O}_3 - \mathcal{O}_5 , \mathcal{O}_7 - \mathcal{O}_{10} , $\mathcal{O}_{12} \rightarrow 0$ as $h \rightarrow 0$. Additionally, by referring the compactness of $T(\rho)$, \mathcal{O}_1 , \mathcal{O}_2 , \mathcal{O}_6 , \mathcal{O}_{11} tends to zero. Therefore

$$\|m(\rho+h) - m(\rho)\| \rightarrow 0$$

when $h \rightarrow 0$ for all $z \in Q_\alpha$, which implies $\mathcal{R}(Q_\alpha) \subset \mathcal{C}$ is equicontinuous.

Step 4: For $\alpha > 0$, fix $W_\alpha = \{z \in \mathcal{Y} : |z| \leq \alpha\}$. Clearly, W_α a bounded subset in \mathcal{Y} . To prove for all $\alpha > 0$ and $\rho > 0$,

$$\mathcal{U}(\rho) = \left\{ \int_0^\infty a\rho J^{-1}S_a(\rho)S(\rho^a\rho)z d\rho, z \in W_\alpha \right\},$$

are relatively compact in \mathcal{Y} .

Assume that $\rho > 0$ be determined. For every $\delta > 0, 0 < \varepsilon \leq \rho$, determine a subset in \mathcal{Y} by

$$\mathcal{U}_{\varepsilon, \delta}(\rho) = \left\{ \frac{S(\varepsilon^a \delta)}{\varepsilon^a \delta} \int_{\delta}^{\infty} a \rho J^{-1} S_a(\rho) S(\rho^a \rho - \varepsilon^a \delta) z d\rho, \quad z \in W_a \right\}.$$

Clearly for every $\rho > 0, \mathcal{U}_{\varepsilon, \delta}(\rho)$ is clearly defined. Indeed, referring uniform convergence of Mainardi's Wright-type function $\rho \in (\delta, \infty)$ and uniform boundedness of cosine family and, we get for every $z \in W_a$,

$$\begin{aligned} \left| \frac{S(\varepsilon^a \delta)}{\varepsilon^a \delta} \int_{\delta}^{\infty} a \rho J^{-1} S_a(\rho) S(\rho^a \rho - \varepsilon^a \delta) z d\rho \right| &\leq \tilde{J}_1 P^2 |z| \int_{\delta}^{\infty} a \rho S_a(\rho) (\rho^a \rho + \varepsilon^a \delta) d\rho \\ &\leq 2\tilde{J}_1 P^2 |z| \rho^a \int_{\delta}^{\infty} a \rho^2 S_a(\rho) d\rho \leq \frac{2\tilde{J}_1 P^2}{\Gamma(2a)} |z| \rho^a. \end{aligned}$$

Therefore, $\mathcal{U}_{\varepsilon, \delta}(\rho)$ is relatively compact because $S(\varepsilon^a \delta)$ is compact for $\varepsilon^a \delta > 0$.

Additionally,

$$\begin{aligned} &\left| \frac{S(\varepsilon^a \delta)}{\varepsilon^a \delta} \int_{\delta}^{\infty} a \rho J^{-1} S_a(\rho) S(\rho^a \rho - \varepsilon^a \delta) z d\rho - \int_0^{\infty} a \rho J^{-1} S_a(\rho) S(\rho^a \rho) z d\rho \right| \\ &\leq \left| \frac{S(\varepsilon^a \delta)}{\varepsilon^a \delta} \int_{\delta}^{\infty} a \rho J^{-1} S_a(\rho) S(\rho^a \rho - \varepsilon^a \delta) z d\rho - \int_0^{\infty} a \rho J^{-1} S_a(\rho) S(\rho^a \rho) z d\rho \right| \\ &\quad + \left| \int_{\delta}^{\infty} a \rho J^{-1} S_a(\rho) S(\rho^a \rho) z d\rho - \int_0^{\infty} a \rho J^{-1} S_a(\rho) S(\rho^a \rho) z d\rho \right| \\ &\leq \int_{\delta}^{\infty} a \rho \tilde{J}_1 S_a(\rho) \left| \frac{S(\varepsilon^a \delta)}{\varepsilon^a \delta} S(\rho^a \rho - \varepsilon^a \delta) z - S(\rho^a \rho) z \right| d\rho + \int_0^{\delta} a \rho \tilde{J}_1 S_a(\rho) |S(\rho^a \rho) z| d\rho \\ &:= l_1 + l_2. \end{aligned}$$

Since

$$a \rho \tilde{J}_1 S_a(\rho) \left| \frac{S(\varepsilon^a \delta)}{\varepsilon^a \delta} S(\rho^a \rho - \varepsilon^a \delta) z - S(\rho^a \rho) z \right| \leq 2\tilde{J}_1 P^2 \rho^a a \rho^2 S_a(\rho) |z|,$$

and

$$\int_0^{\infty} a \rho^2 \tilde{J}_1 S_a(\rho) d\rho = \frac{2\tilde{J}_1}{\Gamma(1 + 2a)},$$

we can see that

$$\int_0^{\infty} a \rho \tilde{J}_1 S_a(\rho) \left| \frac{S(\varepsilon^a \delta)}{\varepsilon^a \delta} S(\rho^a \rho - \varepsilon^a \delta) z - S(\rho^a \rho) z \right| d\rho,$$

is uniformly convergence. Since from the strongly continuous of sine family $\{S(\rho)\}_{\rho > 0}$, where $\rho \in (\delta, \infty)$, by referring Lemma 2.12, we have

$$\begin{aligned} &\left| \frac{S(\varepsilon^a \delta)}{\varepsilon^a \delta} S(\rho^a \rho - \varepsilon^a \delta) z - S(\rho^a \rho) z \right| \\ &\leq \left| \frac{S(\varepsilon^a \delta)}{\varepsilon^a \delta} S(\rho^a \rho - \varepsilon^a \delta) z - S(\rho^a \rho - \varepsilon^a \delta) z \right| + |S(\rho^a \rho - \varepsilon^a \delta) z - S(\rho^a \rho) z| \rightarrow 0, \end{aligned}$$

when $\delta \rightarrow 0$. Therefore, we have

$$l_1 \leq \int_0^{\infty} a \rho \tilde{J}_1 S_a(\rho) \left| \frac{S(\varepsilon^a \delta)}{\varepsilon^a \delta} S(\rho^a \rho - \varepsilon^a \delta) z - S(\rho^a \rho) z \right| d\rho \rightarrow 0, \quad \text{as } \delta \rightarrow 0.$$

However, by $\int_0^{\delta} a \rho^2 \tilde{J}_1 S_a(\rho) d\rho \rightarrow 0$ when $\delta \rightarrow 0$, we have

$$l_2 \leq \tilde{J}_1 P |z| \rho^a \int_0^{\delta} a \rho^2 S_a(\rho) d\rho \rightarrow 0, \quad \text{when } \delta \rightarrow 0.$$

Thus, there are relatively compact sets arbitrarily close to $\mathcal{U}(\rho)$, for all $\rho > 0$. Thus $\mathcal{U}(\rho)$ is relatively compact in \mathcal{Y} , for all $\rho > 0$.

Step 5: \mathcal{R} has a closed graph.

Assume that $z^n \rightarrow z^*$ when $n \rightarrow \infty$, and $m^n \rightarrow m^*$ when $n \rightarrow \infty$. We shall prove that $m^* \in \mathcal{R}(z^*)$. Since $m^n \in \mathcal{R}(z^n)$, there exists $g^n \in S_{E, z^n}$ such that

$$\begin{aligned} m^n(\rho) &= J^{-1}M_a(\rho)Jz_0 + J^{-1}W_a(\rho)Jz_1 + \int_0^\rho (\rho - i)^{a-1}J^{-1}Q_a(\rho - i)g^n(i)di \\ &\quad + \int_0^\rho (\rho - i)^{a-1}J^{-1}Q_a(\rho - i)\mathcal{B}\mathcal{B}^*J^{-1}Q_a^*(c - \rho)R(\mu, \Gamma_0^c) \left[z_c - J^{-1}M_a(c)Jz_0 \right. \\ &\quad \left. - J^{-1}W_a(c)Jz_1 - \int_0^c (c - \varphi)^{a-1}J^{-1}Q_a(c - \varphi)g^n(\varphi)d\varphi \right](i)di. \end{aligned}$$

We need to show that there exists $g^* \in S_{E, z^*}$ such that for all $\rho \in V$,

$$\begin{aligned} m^*(\rho) &= J^{-1}M_a(\rho)Jz_0 + J^{-1}W_a(\rho)Jz_1 + \int_0^\rho (\rho - i)^{a-1}J^{-1}Q_a(\rho - i)g^*(i)di \\ &\quad + \int_0^\rho (\rho - i)^{a-1}J^{-1}Q_a(\rho - i)\mathcal{B}\mathcal{B}^*J^{-1}Q_a^*(c - \rho)R(\mu, \Gamma_0^c) \\ &\quad \times \left[z_c - J^{-1}M_a(c)Jz_0 - J^{-1}W_a(c)Jz_1 - \int_0^c (c - \varphi)^{a-1}J^{-1}Q_a(c - \varphi)g^*(\varphi)d\varphi \right](i)di, \end{aligned}$$

clearly,

$$\begin{aligned} &\left\| \left(m^n(\rho) - J^{-1}M_a(\rho)Jz_0 - J^{-1}W_a(\rho)Jz_1 - \int_0^\rho (\rho - i)^{a-1}J^{-1}Q_a(\rho - i)\mathcal{B}\mathcal{B}^*J^{-1}Q_a^*(c - \rho) \right. \right. \\ &\quad \left. \left(\times \right) R(\mu, \Gamma_0^c) \left[z_c - J^{-1}M_a(c)Jz_0 - J^{-1}W_a(c)Jz_1 - \int_0^c (c - \varphi)^{a-1}J^{-1}Q_a(c - \varphi)g^n(\varphi)d\varphi \right](i)di \right) \\ &\quad - \left(m^*(\rho) - J^{-1}M_a(\rho)Jz_0 - J^{-1}W_a(\rho)Jz_1 - \int_0^\rho (\rho - i)^{a-1}J^{-1}Q_a(\rho - i)\mathcal{B}\mathcal{B}^*J^{-1}Q_a^*(c - \rho) \right. \\ &\quad \left. \left(\times \right) R(\mu, \Gamma_0^c) \left[z_c - J^{-1}M_a(c)Jz_0 - J^{-1}W_a(c)Jz_1 - \int_0^c (c - \varphi)^{a-1}J^{-1}Q_a(c - \varphi)g^*(\varphi)d\varphi \right](i)di \right) \left. \right\| \end{aligned}$$

$\rightarrow 0$ as $n \rightarrow \infty$. Assume that $\mathcal{T} : L^1(V, \mathcal{Y}) \rightarrow \mathcal{C}$,

$$\begin{aligned} (\mathcal{T}g)(\rho) &= \int_0^\rho (\rho - i)^{a-1}J^{-1}Q_a(\rho - i) \left[g^n(i) + \mathcal{B}\mathcal{B}^*J^{-1}Q_a^*(c - \rho)R(\mu, \Gamma_0^c) \right. \\ &\quad \left. \times \left(\int_0^c (c - \varphi)^{a-1}J^{-1}Q_a(c - \varphi)g^*(\varphi)d\varphi \right)(i) \right] di \end{aligned}$$

clearly, from Lemma 2.14, that $\mathcal{T} \circ S_{E, z}$ is a closed graph operator. Additionally, by referring \mathcal{T} , we have

$$\begin{aligned} &\left(m^n(\rho) - J^{-1}M_a(\rho)Jz_0 - J^{-1}W_a(\rho)Jz_1 - \int_0^\rho (\rho - i)^{a-1}J^{-1}Q_a(\rho - i)\mathcal{B}\mathcal{B}^*J^{-1}Q_a^*(c - \rho)R(\mu, \Gamma_0^c) \right. \\ &\quad \left. \times \left[z_c - J^{-1}M_a(c)Jz_0 - J^{-1}W_a(c)Jz_1 - \int_0^c (c - \varphi)^{a-1}J^{-1}Q_a(c - \varphi)g^n(\varphi)d\varphi \right](i)di \right) \\ &\quad \in \mathcal{T}(S_{E, z^n}) \end{aligned}$$

Because $g^n \rightarrow g^*$, and by referring Lemma 2.14, we have

$$\left(m^*(\rho) - J^{-1}M_a(\rho)Jz_0 - J^{-1}W_a(\rho)Jz_1 - \int_0^\rho (\rho - i)^{a-1}J^{-1}Q_a(\rho - i)\mathcal{B}\mathcal{B}^*J^{-1}Q_a^*(c - \rho)R(\mu, \Gamma_0^c) \right.$$

$$\times \left[z_c - J^{-1}M_a(c)Jz_0 - J^{-1}W_a(c)Jz_1 - \int_0^c (c-\varphi)^{a-1}J^{-1}Q_a(c-\varphi)g^*(\varphi)d\varphi \right] (t) dt$$

$$\in \mathcal{T}(S_{E,z^*})$$

Hence, \mathcal{R} is closed graph.

Hence, by referring **Step 1–5**, and applying Arzela-Ascoli theorem, \mathcal{R} is a completely continuous multivalued mapping with compact value and thus \mathcal{R} is u.s.c. Therefore \mathcal{R} has a fixed point $z(\cdot)$ on Q_α , and in view of Lemma 2.15, $z(\cdot)$ is the mild solution of (1.1)–(1.2). \square

Definition 3.2 The system (1.1)–(1.2) is called approximately controllable on V if $\overline{R(c, z_0)} = \mathcal{Y}$, $R(c, z_0) = \{z_c(z_0; x) : x(\cdot) \in L^2(V, \mathcal{U})\}$ is a solution of (1.1)–(1.2). \square

Theorem 3.3 Assume that $\mathbf{H}_1 - \mathbf{H}_5$ are satisfied. Further, there exists

$$\mathcal{F} \in L^1(V, [0, +\infty)) \text{ such that } \sup_{z \in \mathcal{Y}} \|E(\rho, z)\| \leq \mathcal{F}(\rho)$$

for a.e. $\rho \in V$, then (1.1)–(1.2) is approximately controllable.

Proof. Consider $\hat{z}^\mu(\cdot)$ a fixed point of \mathcal{R} in Q_α . Referring 3.1, any fixed point of \mathcal{R} is a solution of (1.1)–(1.2) with

$$\hat{x}^\mu(\rho) = \mathcal{B}^*J^{-1}Q_a^*(c-\rho)R(\mu, \Gamma_0^c)q(\hat{z}^\mu)$$

and satisfies the following inequality

$$\hat{z}^\mu(c) = z_c + \mu R(\mu, \Gamma_0^c)q(\hat{z}^\mu). \quad (3.5)$$

Further from E and Dunford-Pettis Theorem, we conclude that $\{g^\mu(t)\}$ is weakly compact in $L^1(V, \mathcal{Y})$, so there exists a subsequence, $\{g^\mu(t)\}$, that converges weakly to $g(t)$ in $L^1(V, \mathcal{Y})$. Determine

$$\mathcal{V} = z_c - J^{-1}M_a(c)Jz_0 - J^{-1}W_a(c)Jz_1 - \int_0^c (c-i)^{a-1}J^{-1}Q_a(c-i)g(i)di.$$

Now, we have

$$\begin{aligned} \|q(\hat{z}^\mu) - \mathcal{V}\| &= \left\| \int_0^c (c-i)^{a-1}J^{-1}Q_a(c-i) [g(i, \hat{z}^\mu(i)) - g(i)] di \right\| \\ &\leq \sup_{\rho \in V} \left\| \int_0^c (c-i)^{a-1}J^{-1}Q_a(c-i) [g(i, \hat{z}^\mu(i)) - g(i)] di \right\|. \end{aligned} \quad (3.6)$$

By Ascoli-Arzela theorem, we can prove

$$\mathcal{L}(\cdot) \rightarrow \int_0^c (\cdot-i)^{a-1}J^{-1}Q_a(\cdot-i)\mathcal{L}(i)di : L^1(V, \mathcal{Y}) \rightarrow C(V, \mathcal{Y})$$

is compact. Hence, we have

$$\|q(\hat{z}^\mu) - \mathcal{V}\| \rightarrow 0 \text{ when } \mu \rightarrow 0^+.$$

Furthermore, in view of Equation (3.5), we have

$$\begin{aligned} \|\hat{z}^\mu(c) - z_c\| &\leq \|\mu R(\mu, \Gamma_0^c)(\mathcal{V})\| + \|\mu R(\mu, \Gamma_0^c)\| \|q(\hat{z}^\mu) - \mathcal{V}\| \\ &\leq \|\mu R(\mu, \Gamma_0^c)(\mathcal{V})\| + \|q(\hat{z}^\mu) - \mathcal{V}\|. \end{aligned}$$

It follows from \mathbf{H}_0 and (3.6) that

$$\|\hat{z}^\mu(c) - z_c\| \rightarrow 0 \text{ as } \mu \rightarrow 0^+.$$

Therefore the system (1.1)–(1.2) is approximately controllable on V . □

4 | NONLOCAL CONDITIONS

Differential systems with nonlocal conditions have become a very lively field of recent research. Their investigation is driven by hypothetical enthusiasm as well as by the way that these kinds of issues normally happen when demonstrating practical applications. For instance, few events in designing, material science, and life sciences can be portrayed by methods for the differential system subject to nonlocal boundary conditions, and one can refer [6, 9, 11, 14, 16, 18, 25, 32, 37–41]. Consider the nonlocal fractional Sobolev type Volterra-Fredholm integro-differential inclusions of order $r \in (1, 2)$ of the type

$${}^C D_\rho^r (Jz(\rho)) \in Az(\rho) + \mathcal{B}x(\rho) + E\left(\rho, z(\rho), \int_0^\rho e(\rho, s, z(s))ds, \int_0^c h(\rho, s, z(s)) ds\right), \quad \rho \in V, \quad (4.1)$$

$$z(0) + l(z) = z_0, \quad z'(0) = z_1 \in \mathcal{Y}, \quad (4.2)$$

where the function $l : C([0, c], \mathcal{Y}) \rightarrow \mathcal{Y}$ satisfies the following hypothesis:

H₆ The function $l : C([0, c], \mathcal{Y}) \rightarrow \mathcal{Y}$ is compact and continuous, and there exists constants L_1, L_2 such that $\|l(z)\| \leq L_1 \|z\|_C + L_2$, where $z \in C(V, \mathcal{Y})$.

The mild solution of the nonlocal fractional evolution system (4.1)–(4.2) defined as follows:

Definition 4.1 A function $z \in C = C(V, \mathcal{Y})$ is called a solution of (4.1)–(4.2) if $z(0) + l(z) = z_0, z'(0) = z_1, x(\cdot) \in L^2(V, \mathcal{U})$ and there exists $g \in L^1(V, \mathcal{Y})$ such that $g(\rho) \in E(\rho, z(\rho), \int_0^\rho e(\rho, s, z(s))ds, \int_0^c h(\rho, s, z(s))ds)$ on a.e. $\rho \in V$ and

$$z(\rho) = J^{-1}M_a(\rho)J[z_0 - l(z)] + J^{-1}W_a(\rho)Jz_1 + \int_0^\rho (\rho - t)^{a-1}J^{-1}Q_a(\rho - t)\mathcal{B}x(t)dt + \int_0^\rho (\rho - t)^{a-1}J^{-1}Q_a(\rho - t)g(t)dt,$$

is satisfied.

Theorem 4.2 If **H₁–H₆** are satisfied, then the system (4.1)–(4.2) is approximately controllable on V .

5 | EXAMPLE

Let us consider $\chi \subset \mathbb{R}^N$ be an open C^2 bounded domain. Assume that $\mathcal{Y} = \mathcal{U} = L^2(\chi)$. Let us assume the fractional integro-differential system

$$\partial_\rho^r (u(\rho, v) - \Delta u(\rho, v)) \in \Delta u(\rho, v) + \hat{h}(\rho, v) + P\left(\rho, u(\rho, z), \int_0^\rho e(\rho, s, u(\rho, z))ds, \int_0^c h(\rho, s, u(\rho, z))ds\right), \quad \rho \in [0, 1], v \in \chi, \quad (5.1)$$

$$u(\rho, v) = 0, \quad \rho \in [0, 1], \quad v \in \partial\chi, \quad (5.2)$$

$$u(0, v) = u_0(v), \quad u'(0, v) = u_1(v), \quad v \in \chi. \quad (5.3)$$

In the above, ∂_ρ^r is the partial derivative in Caputo sense of fractional order $r \in (1, 2)$. Let us consider $V = [0, 1]$. Assume that A be the Laplace operator with Dirichlet boundary conditions given as $Au = \Delta$ and assume $A : D(A) \subset \mathcal{Y} \rightarrow \mathcal{Y}, J : D(J) \subset \mathcal{Y} \rightarrow \mathcal{Y}$ be the operators defined by $Au = \Delta$, and $Ju = u - \Delta$ where each domain $D(A)$ and $D(J)$ is presented by

$$D(A) = D(J) = \{g \in H_0^1(\chi), Ag \in L^2(\chi)\}.$$

It is clear that $D(A) = H_0^1(\chi) \cap H^2(\chi)$. Obviously A gives a uniformly bounded C_0 cosine family $C(\rho)$ for $\rho \geq 0$, refer [42]. Indeed, let $t_n = n^2\pi^2$ and $\psi_n(v) = \sqrt{\frac{2}{\pi}} \sin(n\pi v)$, for all $n \in \mathbb{N}$ are the orthonormal of vectors of A .

Assume $\{-t_n, \psi_n\}_{n=1}^\infty$ is the eigensystem of the operator A , then $0 < t_1 \leq t_2 \leq \dots, t_n \rightarrow \infty$ as $n \rightarrow \infty$, and $\{\psi_n\}_{n=1}^\infty$ create the orthonormal basis of \mathcal{Y} . Now

$$Au = \sum_{n=1}^\infty t_n \langle u, \psi_n \rangle \psi_n, \quad u \in D(A),$$

$$Ju = \sum_{n=1}^\infty (1 + t_n) \langle u, \psi_n \rangle \psi_n, \quad u \in D(J).$$

Additionally, for $z \in \mathcal{Y}$, we have

$$J^{-1}u = \sum_{n=1}^\infty \frac{1}{(1 + t_n)} \langle u, \psi_n \rangle \psi_n,$$

$$AJ^{-1}u = \sum_{n=1}^\infty \frac{t_n}{(1 + t_n)} \langle u, \psi_n \rangle \psi_n,$$

where $\langle \cdot, \cdot \rangle$ stands for inner product in \mathcal{Y} . Accordingly, we now define the cosine family by

$$C(\rho)u = \sum_{n=1}^\infty \cos(\sqrt{t_n}\rho) \langle u, \psi_n \rangle \psi_n, \quad u \in \mathcal{Y},$$

which is connected with sine family $S(\rho)$ compact for $(\rho > 0)$ as follows

$$S(\rho)y = \sum_{n=1}^\infty \frac{1}{\sqrt{t_n}} \sin(\sqrt{t_n}\rho) \langle y, \psi_n \rangle \psi_n, \quad y \in \mathcal{Y}.$$

It is not difficult to verify $\|C(\rho)\|_{L_c(\mathcal{Y})} \leq 1$, for all $\rho \in \mathbb{R}$.

Let us assume $u(\rho) = u(\rho, \cdot)$, that is, $u(\rho)(v) = u(\rho, v)$, $\rho \in [0, 1]$, and $x(\rho) = \hbar(\rho, \cdot)$, consider $\hbar : [0, 1] \times \chi \rightarrow \chi$ is continuous. Determine $\mathcal{B} : \mathcal{U} \rightarrow \mathcal{Y}$ by $\mathcal{B}x(\rho)(v) = \hbar(\rho, v)$. We now define

$$E\left(\rho, u(\rho), \int_0^\rho e(\rho, s, u(s)) ds, \int_0^c h(\rho, s, u(s)) ds\right)(z)$$

$$= P\left(\rho, u(\rho, z), \int_0^\rho e(\rho, s, u(\rho, z)) ds, \int_0^c h(\rho, s, u(\rho, z)) ds\right).$$

Therefore, entire needs of Theorem 3.1 are satisfied, hence (5.1)–(5.3) is approximately controllable on V .

6 | CONCLUSION

In our article, we primarily concentrated on approximate controllability results for fractional Sobolev type Volterra-Fredholm integro-differential inclusions of order $r \in (1, 2)$. By applying the results and ideas belongs to the cosine function of operators, fractional calculus and fixed point approach, the main

results are established. Initially, we established the approximate controllability of the considered fractional system, then continued to examine the system with the concept of nonlocal conditions. Finally, we presented an example to demonstrate the theory.

CONFLICT OF INTEREST

None declared.

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